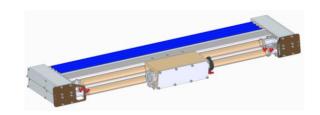


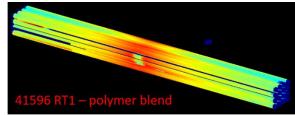
UK Research and Innovation

Boron Coated Straw Tubes for LoKI

Davide Raspino 27/10/2019



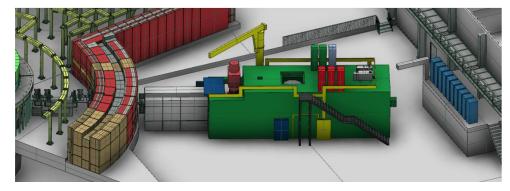




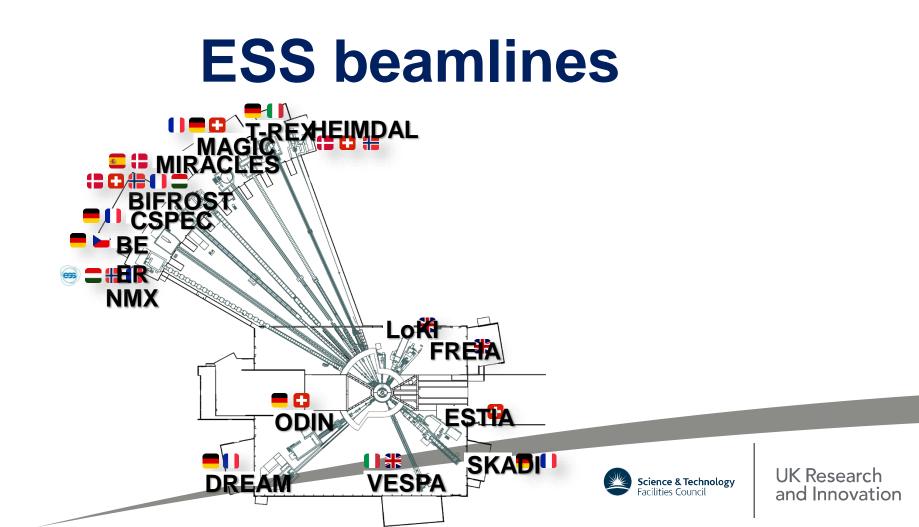
Outline

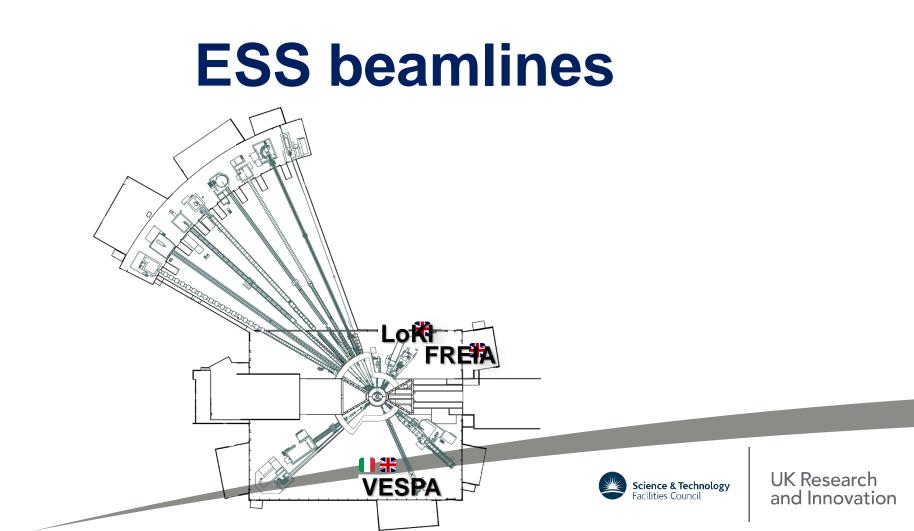


- LoKI introduction
- Detector technology description
 - Detector module
 - Performance
- Readout
 - Multiplexing
 - ADC and signal processing
- SANS test on Larmor

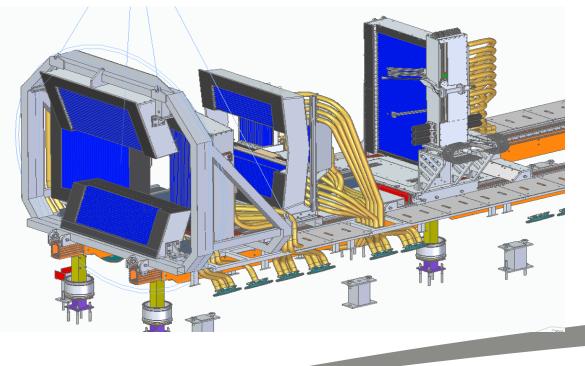








LoKI detector array



~9m² detector area

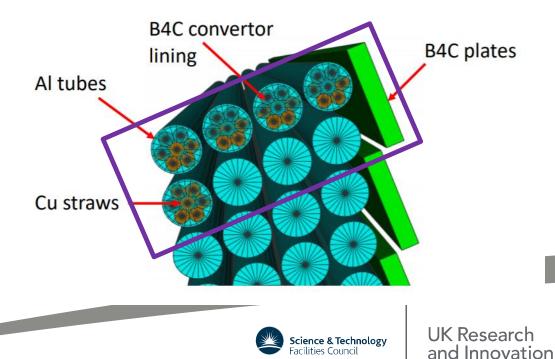
9 panels

5 panel on day 1

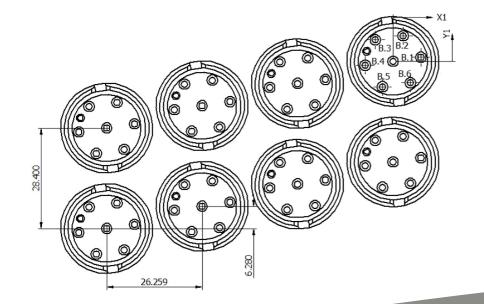


Boron Coated straw tubes

- Produced by Proportional Technology (US)
- Large application in homeland security
- Seven boron coated straws inside a 1" aluminium tube
- Resistive wire as the ³He detector used on most SANS instruments around the world
- Four layers to reach an efficiency comparable to the 8 mm Ø ³He detectors



1" Tubes in a module

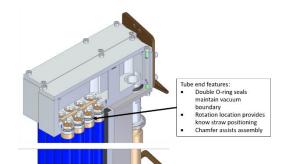


HOLE TABLE		
HOLE	Х	Y
B.1	7.67	1.14
B.2	2.85	7.21
B.3	-4.82	6.07
B.4	-7.67	-1.14
B.5	-2.85	-7.21
B.6	4.82	-6.07

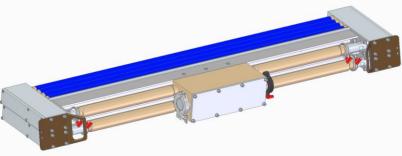




Detector Module



Double conductive O-ring stack (shown in purple) provides flexibility to absorb assembly tolerances and maintains electrical contact between the imaging tubes and air boxes.





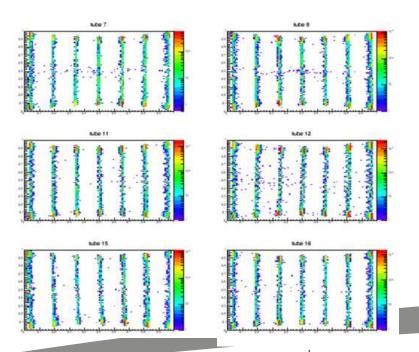


Modules in the detector arrav



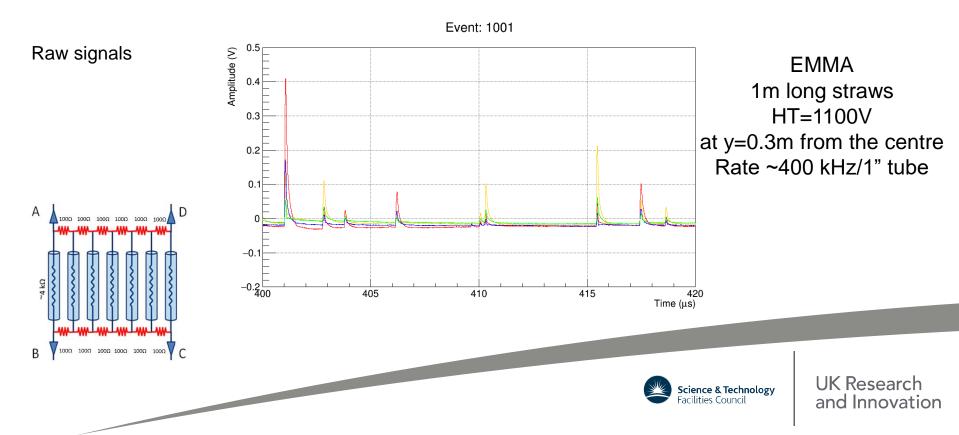
Multiplexing

- Reduce the number of readout channels
- *x* to identify the straw
- *y* gives the position along the straw
- 100Ω resistance, optimised for straw ID
- It fits inside the ends of the tube
- Leaps to guarantee that they all sit at the same height/good connection with the HT boards
- Pogo pins to connect to the HT board
- Sockets to connect to the straws

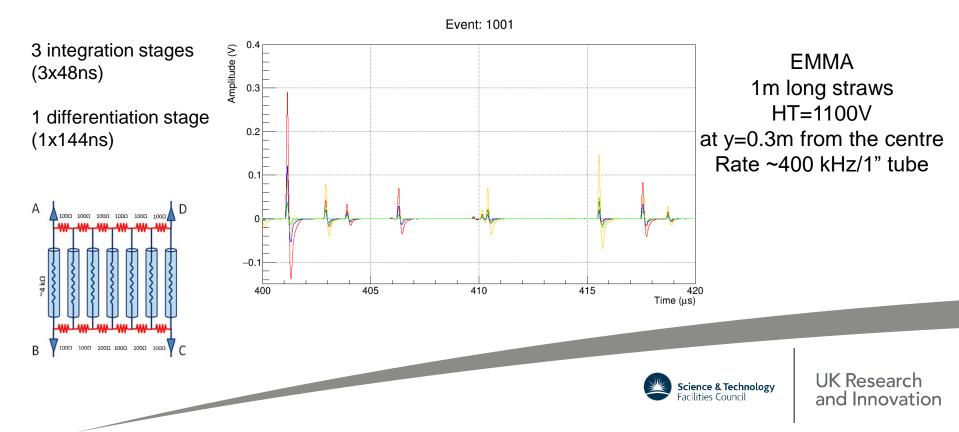




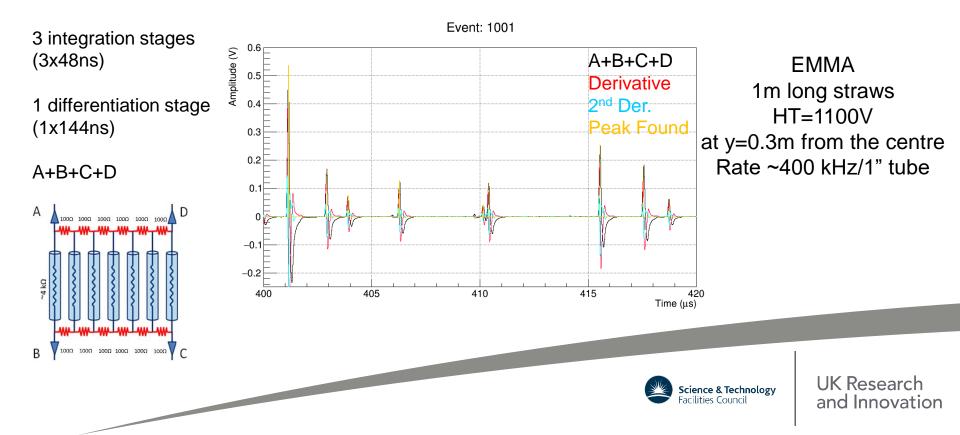
Analog Signals (A-B-C-D)



Analog Signals (A-B-C-D)

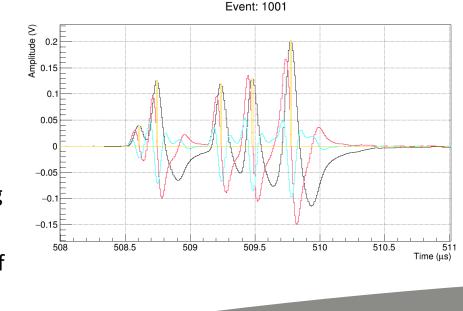


Sum Signals



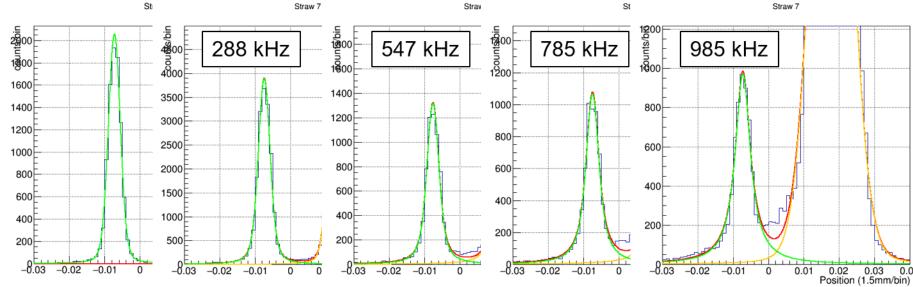
Signal Processing

- 3 integration stages (3x48ns)
- 1 differentiation stage (1x144ns)
- 1. Trigger on 2nd derivative
- 2. Peak at zero crossing on the derivative
- 3. End of the signal at 2nd der. zero crossing
- Amplitudes on A,B,C and D at the time of the peak of the sum





Position Resolution vs Rate

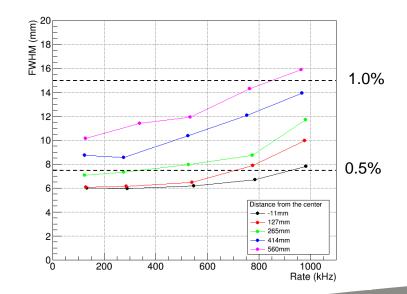


- 1500 mm long straws
- HT=1100V
- 3x48ns int.time
- 144ns diff.time
- 1.5mm Cd Slit



Position Resolution vs Rate

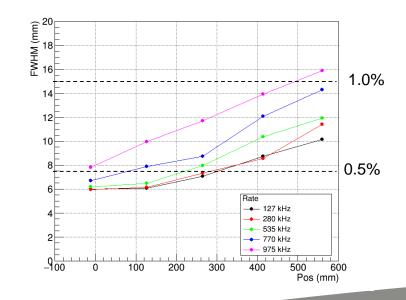
- 1500 mm long straws
- HT=1100V
- 3x48ns int.time
- 144ns diff.time
- 1.5mm Cd slit





Position Resolution vs Position

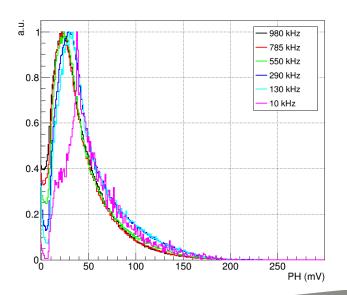
- 1500 mm long straws
- HT=1100V
- 3x48ns int.time
- 144ns diff.time





PH vs Rate

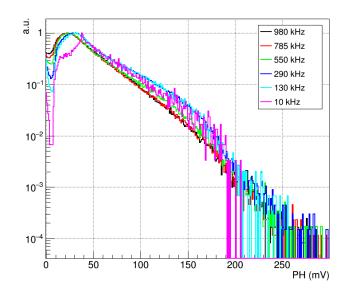
- 1500 mm long straws
- HT=1100V
- 3x48ns int.time
- 144ns diff.time





PH vs Rate

- 1500 mm long straws
- HT=1100V
- 3x48ns int.time
- 144ns diff.time





ADC

- CAEN/NI R5560 with Xilinx Zynq Z-7035
 FPGAs
- 128 input Channels
- Digitise the signals (125MHz)
- Open FPGA
- Signal processing
- Straw ID
- Position Calculation
- Time Stamp
- Create a data package
- Transmit data to the back end electronics
- Visualisation of analogue signals

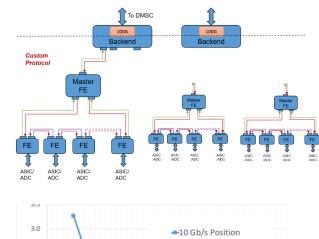


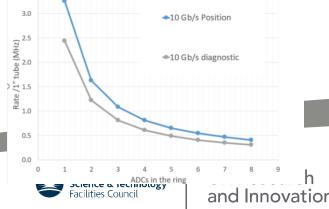




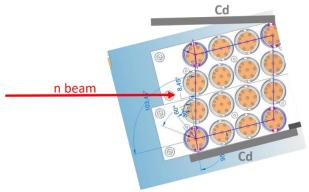
ADC to BackEnd electronics

- 18 ADCs \rightarrow 6 rings \rightarrow 3 ADCs/ring
 - it is enough for the foreseen neutron rate
 - it will allow to keep the same configuration when the full detector coverage will be available
 - Still using 1 back end electronics board
- Time stamp precision requirement ~100μs
 - 64 bit precision 14ns
 - 52 bit precision 57.3µs
- 32 bits packet transmission around the ring
- Communication between neighbour FPGA possible via fast link firmware to be done
- Interface the ADC with the FEA and the Backend Electronics together with STFC TD

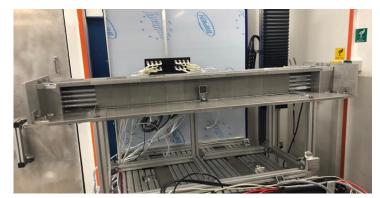




SANS test on Larmor



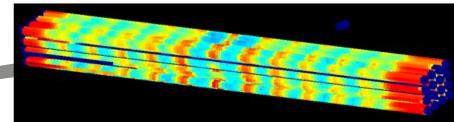
- 1.5 m long straws
- HT=950V
- ADC in diagnostic/event mode
- Ethernet readout
- Calibration mask for position corrections
- Data corrected and Transformed in histogram mode and loaded in Mantid



(i) Single tube containing 7 BCSs

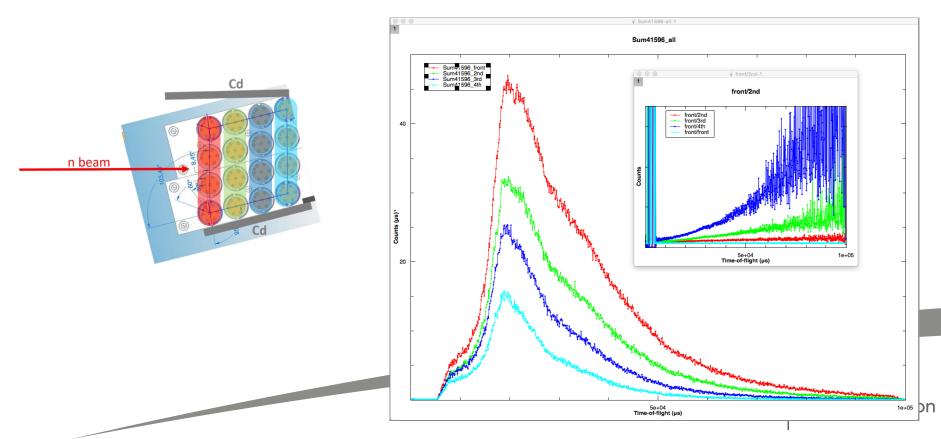


(ii) 16 tubes

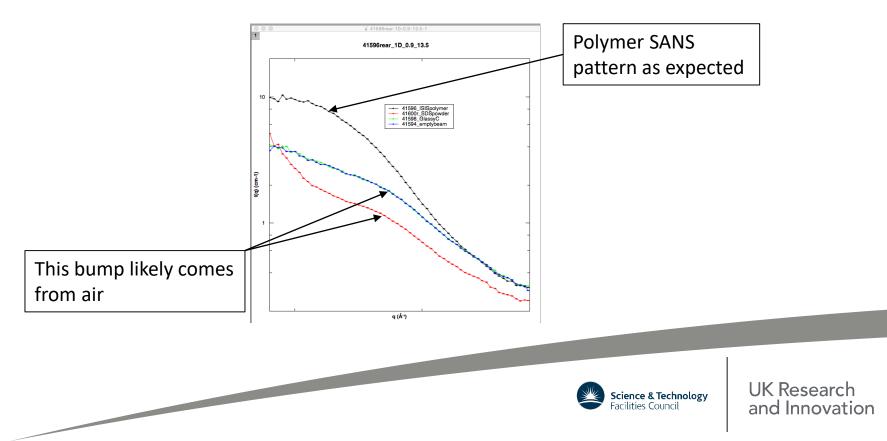


earch ovation

SANS test on Larmor



SANS test on Larmor



Next steps

